# AEMB 32-bit Microprocessor Core Datasheet

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# 1 Introduction

The AEMB is a clean room implementation of the EDK3.2 software compatible Microblaze core using information from the Internet. It is cycle and instruction compatible to the MB for most software commands. It is not meant as a drop in replacement for the Microblaze as it is not architecturally compatible. It uses the WISHBONE bus instead of LMB/OPB.

This is a CPU core that is capable of moving and manipulating data to and from memory. It does not have any peripherals nor interrupt controllers although support for external interrupts is provided. Any peripherals and their respective registers could be mapped to the data memory space. It has a separate instruction, data and FSL bus.

This core is fairly similar to the original Microblaze from the point of view of software. Therefore, this list of features are mainly for the benefit of people unfamiliar with the original Some of the main features are:

- 1. Harvard architecture with a separate 32-bit instruction and data busses. The address space for each bus can be separately configured with core parameters.
- 2. Pipelined operation with a 3-stage integer pipeline. The pipeline is capable of executing one instruction per clock. This short pipeline allows it to context switch quickly.
- 3. Support for hardware multiplier and barrel shifter. Implementation of a single cycle multiplier and barrel shifter will improve software performance.
- 4. Support for GET/PUT instructions. The GET/PUT instructions are implemented as a separate FSL bus. Other peripherals or FIFOs can be connected to this bus.
- 5. Small core size with an excellent performance. It has an equivalent gate count of about 38k gates at 136 MHz in a Xilinx Virtex4 FPGA (without multiplier).
- 6. Mature software development toolchain as it is software compatible with the original. Operating system support for the original core includes uClinux/FreeRTOS.

# 2 External Signals

The core uses a WISHBONE compatible bus for it's on-chip bus. It is cycle compatible with WISHBONE classic cycles. This allows the core to be quickly integrated with many other devices that use this bus. It supports the main legacy bus signals. In addition to this, it also uses some other signals that are described below.

## 2.1 Ports

The core ports are broken into four groups: Instruction Bus, Data Bus, FSL Bus and System signals. They are all listed in table 2.1 with short descriptions. All the signals are active high as per WISHBONE documentation.

The signal functions should all be quite self explanatory. For detailed cycle arbitration and timings, please refer to the official WISHBONE specifications. Some of the WISHBONE signals are missing as they may not be necessary like the write-enable signal for the instruction bus.

	~	- 10	
NAME	SIZE	I/O	DESCRIPTION
IWB_ADR_O	30	Out	Instruction bus address
IWB_STB_O	1	Out	Instruction bus request/strobe
IWB_DAT_I	32	In	Instruction bus data word
IWB_ACK_I	1	In	Instruction bus acknowledge
DWB_ADR_O	30	Out	Data bus address
DWB_DAT_O	32	Out	Data bus data write word
DWB_STB_O	1	Out	Data bus request/strobe
DWB_WRE_O	1	Out	Data bus write/read enable
DWB_SEL_O	4	Out	Data bus byte lane select
DWB_DAT_I	32	In	Data bus data read word
DWB_ACK_I	1	In	Data bus acknowledge
FSL_ADR_O	13	Out	FSL bus address
FSL_DAT_O	32	Out	FSL bus data write word
FSL_STB_O	1	Out	FSL bus request/strobe
FSL_WRE_O	1	Out	FSL bus write/read enable
FSL_DAT_I	32	In	FSL bus data read word
FSL_ACK_I	1	In	FSL bus acknowledge
SYS_INT_I	1	In	Positive edge triggered interrupt
SYS_CLK_I	1	In	Master clock signal
SYS_RST_I	1	In	Master active low reset

Table 2.1: External signal names and descriptions.

# 3 Architecture Blocks

The top-level core (CORE) has a separate instruction and data memory bus without cache memory. This can be used as part of an SoC with internal devices attached to the data memory bus. It is also the main top-level core as it contains all the functional sub-blocks. There are two top-level cores supplied.

### 3.1 Top Level Cores

All designs should use the EDK32 top level core. The old CORE top level is only available for compatibility reasons. It will be eventually phased off once the EDK32 top level core matures. The CORE top level will no longer be supported.

#### **3.2** Core Parameters

The EDK32 core includes an optional hardware multiplier and barrel shifter. The optional hardware components are configured using core parameters. The width of both the instruction and data bus can be specified in the core parameters.

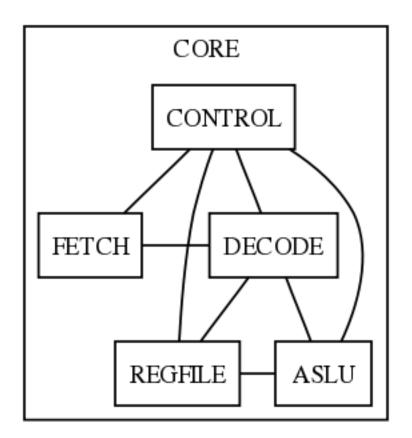


Figure 3.1: AEMB block hierarchy and links

# 4 Functional Operation

Although functionally similar to the Microblaze, the AEMB is not a drop-in substition. The AEMB can be used as an alternative core that can execute compatible code. This chapter documents some of the operation details of the core.

### 4.1 Reset Operation

The master reset signal for the core is SYS\_RST\_I. During reset, all the internal registers for the core are set to their reset values. All interrupts are disabled by the MSR\_IE register value. After reset, the processor begins to fetch instructions from memory location 0x00000000.

#### 4.2 Pipeline Operation

The integer pipeline for the AEMB is a single issue and in-order execution pipeline. It consists of three main stages: *FETCH* & *DECODE*, *LOAD* & *EXECUTE* and *BRANCH* & *STORE*. Each stage is synchronised onto the positive edge SYS\_CLK\_I signal.

Stalls The pipeline is stalled for *any* incomplete memory operation. This means that, unless the memory is fast enough, the processor will stall the entire pipeline. This includes both instruction and data memory access. During a branch it is possible for the AEMB to use a branch delay slot.

#### 4.3 Interrupt Operation

The core has support for positive edge triggered interrupt on the SYS\_INT\_I signal. The interrupt latency is between 3-5 cycles. Interrupts will not trigger between non-atomic instructions such as IMMI.

# 5 Software & Simulation

The AEMB core is capable of executing C code compiled with the Microblaze GCC toolchain. Development of the core was simulated using GPLCVER 2.11a and Icarus Verilog 0.8.5 simulators. Simulatio code was compiled with GCC 3.4.1 (Xilinx EDK 8.1.01 Build EDK\_I.19.4 061107). However, since the core does not implement certain instructions, certain compilation flags should be used.

```
$ mb-gcc -g -mxl-soft-div -msoft-float
```

Some of the hardware components are parameterisable. If a hardware multiplier and barrel shifter is available, other compilation flags can be used to speed up software performance.

#### \$ mb-gcc -g -mno-xl-soft-mul -mxl-barrel-shift

An example compilation script is provided in the /sw/gccrom shell script. This script takes any optional GCC arguments including the C filename. It will generate a suitable simulation ROM and place it in the /sim/aeMB.rom file. The  $/sw/c/aeMB\_testbench.c$ file shows an example C algorithm to calculate Fibonnaci numbers.

### \$ ./gccrom c/aeMB\_testbench.c

The /sim/verilog/testbench.v verilog file is an example simulation testbench. This simulation will load and run the software that is located in the rom file. It is highly tailored to run tests based on the example testbench C code. The /sim/cversim and /sim/iversim are scripts to run the simulation with either CVER or Icarus verilog. These scripts take the programme arguments as well as the simulation testbench file to use.

### \$ ./cversim verilog/edk32.v

 $! \rightarrow$  All these files are provided as examples and should be used as a baseline. For user applications, custom C software and testbench code should be written, which can be based on these files and scripts.

#### Implementation 6

Device utilization summary:

These non-constrained synthesis results from Xilinx ISE v9.1i are !  $\rightarrow~$  for the core. These are not a benchmark but are useful as an estimate of chip resources and performance.

The core has been envisioned to be used as part of a larger SoC. Hence, it has been designed with a small size as an objective.

It is possible to further optimise the design as the critical path runs through the main ALU. About 44% of this critical path is due to routing, not logic.

1%

9%

3%

------Selected Device : 4vlx25ff668-12 11% Number of Slices: 1268 out of 10752 Number of Slice Flip Flops: 272 out of 21504 Number of 4 input LUTs: 2082 out of 21504 Number used as logic: 1698 Number used as RAMs: 384 Number of IOs: 248 Number of bonded IOBs: 248 out of 448 55% Number of GCLKs: 1 out of 32 Timing Summary: \_\_\_\_\_ Speed Grade: -12 Minimum period: 7.315ns (Maximum Frequency: 136.710MHz) Minimum input arrival time before clock: 7.404ns Maximum output required time after clock: 4.005ns Maximum combinational path delay: No path found

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